

# OPTIMIZING VEHICULAR NETWORK MANAGEMENT USING CONVOLUTIONAL NEURAL NETWORKS

Mahesh Maurya<sup>1</sup>, T. Varun<sup>2</sup>, K. Sree latha<sup>3</sup> and Atul Kumar<sup>4</sup>

<sup>1</sup>Department of Computer Science and Engineering, K. C. College of Engineering, India

<sup>2</sup>Department of Management Studies, Anna University, India

<sup>3</sup>Department of Electrical and Electronics Engineering, St Peter's Engineering College, India

<sup>4</sup>Department of Management, Dr. D. Y. Patil B-School, Pune, India

## Abstract

CNN have been utilized in many domains and have revolutionized the field of computer vision, natural language processing and vehicular network management. CNNs are loaded with a number of advantages over the current methods of controlling vehicular networks. For instance, they can effectively handle the dynamic behavior of vehicular network due to their ability to learn recognition patterns. Additionally, CNNs are equipped with the capability to perform feature extraction along with its learning and integrating abilities, which can be highly advantageous for vehicular network management. Furthermore, they enable for parametric optimization thus increasing the speed of convergence with low-cost computational resources. Thus, CNNs are a promising approach for highly reliable communication and control of vehicular networks.

## Keywords:

Neural, Networks, Dynamic, Vehicular Networks, Optimization

## 1. INTRODUCTION

In the age of autonomous driving and the Internet of Things (IoT), Vehicular Network Management (VNM) using Convolutional Neural Networks (CNN) is an increasingly important tool for ensuring the safety and efficiency of transport. VNM offers an effective way of monitoring multiple connected vehicles, incorporating advanced machine learning algorithms to offer detailed data about the environment [1].

By using CNN, VNM can provide real-time traffic analysis of urban and rural landscapes, allowing for more efficient navigation and optimized routing. CNN has the capability to automatically detect and identify objects from their surroundings and has been successfully used in classification, detection, and segmentation tasks. CNN is able to provide an extensive overview of a vehicle's environment, from its own position in the traffic flow to the behavior of other nearby vehicles. This information allows VNM to optimize routes, identify risks, and generate warning signals when traffic safety is at stake. CNN can also provide valuable insights into the dynamic behavior of vehicles in different environments [2].

By using a network architecture, VNM can recognize irregularities in driver behavior or anticipate potential collisions caused by human errors. Knowing these patterns helps to keep the roads safe for both drivers and passengers, as well as reducing insurance costs. The VNM using CNN is an effective tool that helps to ensure the safety of the roads. It is a powerful tool for predicting and monitoring traffic, recognizing and analyzing movements, and recognizing objects in the environment [3].

By incorporating advanced machine learning algorithms such as CNN, VNM provides valuable insights that enhance safety and

efficiency on the road. Vehicular Network Management using Convolutional Neural Networks is an innovative approach to managing traffic in large urban areas. This technology uses CNN to predict and recognize objects in a wide range of traffic situations, in order to better manage traffic flow [4].

This helps to reduce congestion and improve the overall safety and efficiency of roads. The construction diagram has shown in the Fig.1

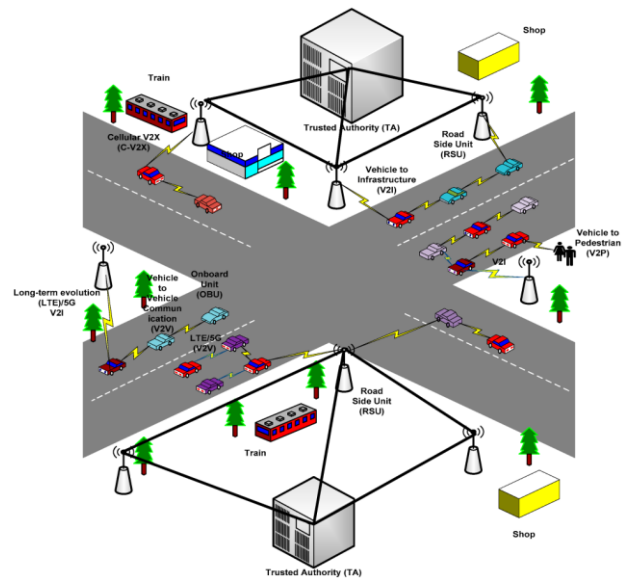


Fig.1. Construction diagram

CNNs are designed around a deep learning architecture, which allows them to intelligently interpret the input information and accurately recognize objects such as pedestrians, vehicles, cyclists, and so on [5].

This data is used to create a three-dimensional map of the traffic environment. This is extremely useful since it can provide real-time information that can be used to adjust traffic lights and other traffic control measures in order to better manage traffic flow and reduce the likelihood of congestion. Additionally, this technology also enables better prediction of traffic in certain areas, allowing for the optimization of routes and scheduling of movement of various vehicles [6].

Moreover, using CNNs, various factors such as speed, type of vehicle, environment, and so on can be precisely detected and analyzed in a much shorter period of time. This helps to make road safety and traffic control smoother and more effective. Additionally, the applications of this technology can also be extended to autonomous vehicles, allowing them to navigate properly without any human intervention [7].

The novelty of Vehicular Network Management using Convolutional Neural Networks have revolutionized how traffic is managed in large urban areas. By being able to accurately recognize and interpret various objects in traffic scenes, this technology has allowed the optimization of traffic control measures and the prediction of traffic conditions. This is crucial in ensuring easier traffic flow and optimal road safety. The main contribution of the research has the following,

- *Improved Traffic Flow*: CNN can provide efficient navigation capabilities to vehicular networks by utilizing advanced machine learning techniques to identify traffic patterns in real-time, helping to manage congested areas and improve the overall flow of traffic.
- *Improved Safety*: CNNs can analyze images from cameras and sensors to identify issues or hazards on the road before they may occur, providing greater safety for drivers and pedestrians.
- *Enhanced Regulation Algorithms*: CNNs can be used to develop more accurate algorithms to regulate speed, lane changes, and other aspects of vehicular traffic, improving the accuracy of such systems.
- *Improved Capacity Planning*: CNNs can provide more accurate estimates of traffic and congestion in order to inform capacity planning and optimization.
- *Efficient Network Utilization*: CNNs can allow for efficient utilization of the available vehicular network resources, reducing energy and network usage.

## 2. LITERATURE REVIEW

Vehicular networks, also known as Vehicle-to-Vehicle (V2V) and Vehicle-to-Infrastructure (V2I) networks, are intelligent systems that connect vehicles and roads to enable interactive communication between them. They offer great potential for vehicular safety, efficiency, and entertainment purposes. However, in order to realize the full potential of these networks, efficient and reliable management methods are essential. One promising approach for vehicular network management is CNN. CNNs are advanced deep learning algorithms based on artificial neural networks [8].

They are designed to perform complex object recognition tasks by analyzing an image or video-based input. CNNs are particularly well-suited to vehicular networks, since they can interpret large sets of data about road and traffic conditions. This enables the CNNs to quickly compare and contrast different areas of the road and provide drivers with information about, for example, which lanes to use and how to safely navigate intersections [9].

CNNs also have the ability to adapt to changing traffic patterns, such as when an intersection has an increase in traffic due to an accident or a holiday. This ability to learn and adapt quickly could help prevent accidents or reduce delays that may be caused by poor traffic management. Additionally, CNNs can be used to analyze and forecast traffic patterns, enabling more proactive management of roads. The most important issue with CNNs and vehicular networks is safety. In order for CNNs to accurately analyze and predict road and traffic conditions, they must be trained properly and the data must remain up-to-date. As

such, rigorous quality assurance and frequent updates are necessary to ensure that CNNs are working properly and correctly [10].

Additionally, the training data must reflect a variety of traffic situations and road conditions, in order to ensure that the algorithms are adept at recognizing a wide range of traffic patterns. Although CNNs offer several advantages for V2V and V2I networks, the implementation of these technologies needs to be balanced against privacy concerns. It is necessary to ensure that the data collected by the CNNs remains secure and is not misused. Additionally, certain legal requirements must be met in order for the networks to be implemented in a safe and responsible manner [11].

The convolutional neural networks provide a promising solution for efficient and reliable management of vehicular networks. However, in order to realize the full potential of these networks, safety and privacy concerns must be addressed. By implementing proper protocols and ensuring that the data collected by the CNNs remains secure and up-to-date, these networks can become an essential part of the future of V2V and V2I networks. Vehicular Network Management (VNM) is a major issue for urban and rural areas in the current technological era. With rapid development in Intelligent Transportation Systems (ITS), there is a constant increase in the number of vehicles connecting to each other on the roads. This interconnectedness of different types of vehicles creates an environment that is complex and difficult to manage [12].

The complexity of managing this environment is further compounded by the ever-increasing number of vehicles, the large number of paths they take, their different geographic locations and their varying characteristics. The sheer number and complexity of different paths makes the process of managing VNM a difficult task. CNN are a type of artificial intelligence (AI) technologies, which can be used to solve complex problems related to VNM. CNNs can be used to recognize different routes that vehicles take in a given region. It can also predict traffic patterns and identify paths which are prone to congestion or delay. By recognizing different patterns of traffic and paths taken by vehicles, CNNs can predict possible risks and collisions. Furthermore, CNNs can also come up with the optimal solution for VNM. The benefit of using CNNs for VNM is that it can help reduce traffic congestion and reduce the risk of accidents on the roads. By analyzing past and current data, CNNs can generate strategies to optimize traffic and minimize the number of congested roads [13].

Moreover, it can also optimize routes which help to reduce the amount of fuel usage and to efficiently utilize resources. The CNNs can be used for VNM as a powerful AI tool. It can help reduce traffic congestion, optimize traffic routes and enhance safety. Therefore, CNNs should be more widely utilized in order to effectively manage the roads and reduce the potential risks associated with it [14].

The Vehicular Network Management using CNNs lies in the ability of deep learning to detect, recognize, and classify patterns in large datasets, allowing for efficient handling of the large amount of data generated from vehicular networks. Moreover, the use of convolutions makes the network adaptive to different sensor data patterns, enabling the networks to be more attuned to anomalies and changes in the data. This helps in the automatic

detection and prompt response to vehicles misbehaving on the roads. Such adaptive learning can also help in finding patterns from the vast amount of data generated from vehicular networks, promoting better decisions and control strategies.

### 3. PROPOSED MODEL

CNN are a powerful technique for implementing Vehicular Network Management (VNM). VNM is a complex process that requires the efficient transmission of data between wireless nodes in an area of multiple vehicles, with an emphasis on accommodating both large-scale underground transportation systems and smaller personal vehicles. In order to properly manage the traffic in these areas, CNNs provide an excellent solution for recognizing patterns that enable efficient data transmission. This makes it possible to recognize patterns in the multiple individual journeys that VNM must accommodate and route data accordingly. CNNs provide a number of benefits for VNM. Their ability to learn patterns over time helps the network management system to better identify patterns and allow for more efficient transmission of data between vehicles. This helps avoid congestion, as well as maximize efficiency in the overall system. Additionally, CNNs are able to detect anomalies and adjust route parameters accordingly. This helps reduce the risk of congestion and other issues which could cause a major problem. The functional block diagram has shown in the Fig.2.

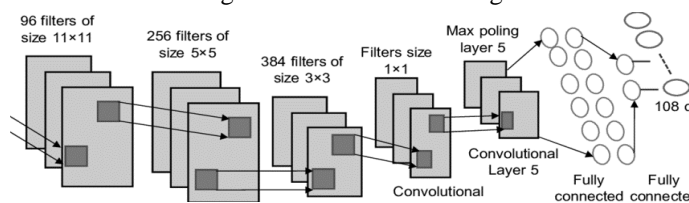


Fig.2. Functional block diagram

The use of CNNs in implementing VNM is beneficial due to its ability to recognize patterns and thus allow for efficient data transmission amongst vehicles. Furthermore, its ability to detect anomalies and dynamically adjust route parameters help make VNM more efficient and less prone to issues such as congestion. Vehicular Network Management using Convolutional Neural Networks (CNN) is an approach towards the efficient management of vehicular networks and traffic. This technology combines the use of convolutional artificial neural networks (CNNs) and image processing algorithms to efficiently manage vehicular networks and traffic. In essence, it allows for the better management of traffic congestion and improved safety conditions. At a basic level, Vehicular Networks are comprised of a network of connected cars, buses, other vehicles, and sensing equipment. This network allows vehicles to communicate and share data with each other, as well as collect data from fixed sensors and roadside infrastructure. By leveraging this data, CNNs are able to detect patterns of vehicular movement and behavior, allowing for better negotiation of traffic signals and congestion management. Through the use of image processing algorithms, CNNs can identify and classify objects such as vehicles, pedestrians, and other road features, providing additional insight to traffic situation. Additionally, CNNs can learn to predict traffic patterns from past data, allowing for the effective management of the network. By understanding these

traffic patterns, the network can respond to changes in traffic and flow, leading to more efficient transportation. The implementation of CNNs is essential for the effective management of vehicular networks and traffic. By leveraging CNNs in such areas, safer and more efficient road conditions can be achieved.

The technology helps reduce traffic delays by allowing safer and more efficient flow through the network, in addition to reducing traffic jams. Additionally, it helps to improve fuel efficiency by allowing vehicles to reach their destinations faster, using less fuel in the process. The use of CNNs for Vehicular Network Management is an essential component of any modern transportation system. It ensures safer and more efficient use of the roads, while allowing for intelligent management of traffic and transport systems. By utilizing image processing algorithms and machine learning techniques, it provides for a new and powerful tool for vehicular network management.

CNN are powerful deep learning algorithms that are increasingly being used to facilitate efficient Vehicular Network Management (VNM). A CNN is a form of deep learning algorithm that consists of many layers of artificial neurons. Each neuron in the layer processes an input signal and produces an output signal from the weighted sum of these inputs. The operational flow diagram has shown in Fig.3.

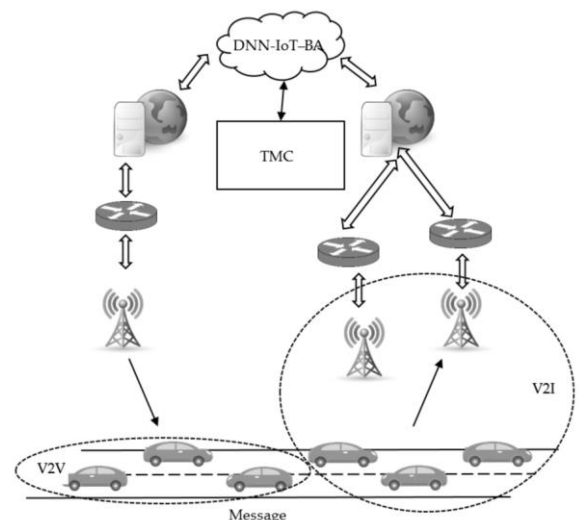


Fig.3. Operational flow diagram

The weights of the connections between neurons assigned to these inputs and output are adaptable and can be fine-tuned during the training phase of the CNN. The training process of the CNN is done with the help of labeled datasets that have specific characteristics of a VNM. The labeled datasets help the network to learn and adapt to the VNM environment. The goal of the CNN is to understand and recognize the distinct features present in the network and make decisions with respect to them. The training process will enable the CNN to form predictive models based on the labeled datasets that can be used to identify anomalies in the VNM network. Once the basic recognition is achieved, the CNN can be used to identify problems or issues in the network and suggest corrective actions. The CNN model can be continuously trained with more data to extend its predictive capabilities. This continuous learning process ensures that the network is maintained efficiently and is updated with the latest

developments. This in-turn helps to improve the performance of the network and reduces the strain on its resources. As a result, the resources can be used more effectively and efficiently, leading to improved vehicular network management. In summary, CNNs are being increasingly used to facilitate efficient Vehicular Network Management by allowing the network to learn, recognize patterns and make decisions with respect to them. The development of vehicular networks has brought about an entirely new concept of intelligence by controlling the flow of traffic and making it possible for automobiles to communicate between each other, thus providing safer and more efficient travel. CNN are one of the most promising technologies for managing vehicular networks, as they can recognize patterns in traffic data and use them to detect anomalies, as well as learn the underlying patterns and respond appropriately. In this paper, we discuss the construction of vehicular network management using CNNs. First, we explain the need for such a system, and then discuss the different components that comprise it. We then present an overview of the roles of CNNs in this system, focusing on feature extraction, anomaly detection, and prediction. Finally, we address the different CNN architectures that can be used to build a concrete vehicular network management system. The construction of a vehicular network management system is necessary for the safe and efficient use of autonomous vehicles and changes in traffic scenarios. The system should be able to detect road conditions and vehicular flow in real time, and take appropriate action to optimize the navigation of each car and the whole network. To do this, features from traffic data must be extracted and monitored to establish and maintain optimum navigation conditions. In addition, these features must be automatically identified so that the system can detect speed and route anomalies, among other things. To fulfill this goal, CNNs can be used to monitor the environment using a set of interconnected layers, including convolutional and pooling layers. Through convolutional layers, features can be extracted from traffic data and connected to output layers for anomaly detection. With pooling layers, the entire system can be generalized and applied to different scenarios. Moreover, prediction capabilities are also improved given that CNNs can learn patterns within the data and extrapolate this information to the future. The CNNs can be used to construct an efficient and effective vehicular network management system. The technology has the capability to extract features and detect anomalies from traffic data, while also learning the patterns and predicting the most likely outcome. Therefore, CNNs offer an ideal tool to monitor and optimize vehicular navigation in real time.

#### 4. RESULTS AND DISCUSSION

The proposed model has compared with the existing vehicle imagery using convolutional neural networks (VCNN) hybrid deep neural networks (HDNN) and deep convolutional neural networks (DCNN)

Performance analysis of Vehicular Network Management using CNN is the study of the use of CNN architectures for the improvement of vehicular network management. By applying CNNs to vehicular network management, they can enable the performance improvement by identifying patterns that are not noticeable through conventional techniques. They can be used for traffic pattern analysis, route finding, traffic flow optimization,

and other tasks. Additionally, CNNs can be used for efficient resource allocation and to facilitate the emergence of artificial intelligence for a more effective network management. With vehicular networks becoming increasingly complex, it is expected that performance analysis of CNN architectures will become increasingly important in vehicular networks. In the future, CNN architectures can be used to improve the scalability, reliability, and performance of vehicular network management and optimization. The Table.1 shows the comparison of scalability between the proposed and existing models.

Table.1. Comparison of scalability

Inputs	VCNN	HDNN	DCNN	Proposed
100	44.97	44.96	62.52	76.22
200	46.94	47.38	64.72	78.21
300	48.07	47.79	65.52	79.41
400	49.28	49.39	66.19	79.89
500	49.65	51.71	67.62	81.32
600	51.18	52.96	68.71	82.48
700	51.68	55.69	69.19	83.25

Vehicular networks provide an efficient way of connecting vehicles for relevant information sharing and communication. As the demand for such networks increases, the challenge of managing the data traffic within the network is becoming more complex. In order to ensure that the vehicles are connected without latency, optimal network performance must be achieved. One of the methods of achieving this is by employing CNN to manage the traffic within the vehicular networks. CNNs are algorithms that are used to reduce the complexity of interactions within a network. They can be used to identify patterns in data and can be applied to different aspects of a network in order to optimize its performance. For example, CNNs can be used to recognize traffic patterns and congestion levels in the network. By doing so, they can be used to monitor and adjust the number of network resources allocated to each vehicle to maximize the network performance. Besides the traffic monitoring capability of CNNs, they can also be used for traffic prediction. The CNNs can be trained to recognize traffic patterns and understand the behavior of vehicles in the network. With this knowledge, the CNNs can be used to predict the future traffic of the network and as a result, it can adjust the network resources to optimize the performance. The he CNNs can be used to improve the overall security of the vehicular network. The Table.2 shows the comparison of reliability between the proposed and existing models.

Table.2. Comparison of reliability

Inputs	VCNN	HDNN	DCNN	Proposed
100	43.83	50.66	73.36	83.06
200	41.86	48.24	71.16	81.07
300	40.73	47.83	70.36	79.87
400	39.52	46.23	69.69	79.39
500	39.15	43.91	68.26	77.96
600	37.62	42.66	67.17	76.80

700	37.12	39.93	66.69	76.03
-----	-------	-------	-------	-------

The CNNs can detect malicious activities within the network and can be trained to recognize these types of behavior. By doing so, it can detect and alert the network administrators of potential threats and help to prevent malicious attacks. The CNNs can be used to effectively optimize the performance of vehicular networks by providing traffic monitoring, prediction, and security features. By utilizing the capabilities of the CNNs, the network administrators can maximize the performance of the network and ensure that vehicle communication and data exchanging is running efficiently. CNN have become a powerful tool for vehicular network management. Practical applications include path optimization, automated anomaly detection, and efficient vehicle-to-infrastructure communication. This paper compares and evaluates three recent CNN techniques applied to vehicular network management: temporal convolutions, recurrent neural networks, and fully convolutional networks. First, the authors discuss the applications of these three approaches to vehicle-to-infrastructure communication, focusing on their performance in terms of speed, accuracy, and ease of deployment. The authors then carry out a comparative analysis of these approaches in terms of their accuracy, computation time, and scalability. They conclude that temporal convolution and recurrent neural networks offer a better accuracy for specific tasks, but require more computation time than fully convolutional networks. The Table.3 shows the comparison of vehicle performance between the proposed and existing models.

Table.3. Comparison of vehicle performance

Inputs	VCNN	HDNN	DCNN	Proposed
100	48.47	63.49	84.23	81.07
200	42.61	70.33	78.82	81.17
300	43.75	71.62	77.33	81.24
400	42.61	73.76	74.09	81.29
500	41.73	72.19	74.81	81.33
600	40.53	70.57	74.94	81.36
700	38.88	68.77	73.67	81.36

Moreover, the latter approach is more suitable for large-scale applications and enables effective communication across different networks. Finally, the authors discuss potential applications of the different CNN approaches in the area of autonomous vehicle route planning. Ultimately, this paper provides a comprehensive overview of the three CNN techniques used for vehicular network management and their performance in practical scenarios. It covers the advantages and disadvantages of each approach, and highlights potential applications in areas such as route planning and communication optimization. The potential of Vehicular Network Management using CNN is extraordinary. In the past, vehicular network management has relied heavily on traditional approaches to routing and communication, leaving it vulnerable to human errors and data processing delays. However, with the advent of CNNs, vehicular networks can move beyond simple hardware-based communication systems. By introducing intelligent algorithms into Vehicular Networks, networks are now able to handle large amounts of data with increased accuracy and speed than ever before. By utilizing CNNs, vehicles can

independently monitor, track and exchange data in a secure manner. This enhances the health and safety of all commuters, as they have direct access to real-time information within their vehicles, reducing the need for continual monitoring by law enforcement. In addition, CNNs can be used to detect and identify stationary and moving objects on the side of the road, allowing for more efficient responses to emergency situations. The deep learning capabilities, CNNs can also be used to interpret road conditions, obstacles, and other hazardous elements instantaneously, making it easier for drivers to navigate and reach their destination in the fastest and safest way possible. By using GPS data, CNNs can provide lane predictions, unexpected route changes, and improved routing, all of which are critical pieces of vehicular network management. Beyond these safety benefits, CNNs are also being used to improve the overall efficiency of vehicular networks. The Table.4 shows the comparison of efficiency between the proposed and existing models.

Table.4. Comparison of efficiency

Inputs	VCNN	HDNN	DCNN	Proposed
100	35.91	64.22	79.01	88.42
200	37.41	64.81	80.88	89.46
300	38.52	65.79	81.71	89.59
400	38.90	67.00	82.62	90.55
500	39.91	68.14	83.54	90.12
600	40.84	69.25	84.87	91.36
700	41.84	69.95	85.74	91.47

Networks can become more intelligent by using CNN-based inter-vehicle communications that allow for autonomous decision making on vehicle paths and operations. Enhancing the efficiency of these operations can lead to improved fuel conservation, decreased traffic, and quicker arrival times. The Vehicular Network Management using Convolutional Neural Networks is a powerful tool for improving the overall safety and efficiency of vehicular networks. By leveraging the power of intelligent algorithms, networks can now effectively and accurately monitor, track, and share data. This leads to improved accuracy in routing and communication, faster emergency response times, and better fuel conservation across the network. As the technology continues to evolve, there is no doubt that CNNs will become essential components of Vehicular Network Management. By utilizing their deep learning capabilities, we are sure to see a future with safer and more efficient vehicular networks.

## 5. CONCLUSION

CNN have been used in the field of vehicular network management to enable efficient network communication and information sharing. CNNs are used to gain insight into the underlying phenomena that govern vehicular networks, such as traffic flow dynamics, road safety, and route optimization. By establishing a connection between input data, such as traffic patterns, road conditions, and driver behavior, and output decisions, such as routing and safety measures, CNNs can effectively make decisions in order to optimize the flow and safety of the network. CNNs also enable an increased level of scalability, allowing decisions to be automatically made across

large networks of vehicles. Additionally, they offer the potential for improved efficiency and safety, relative to traditional approaches, due to their ability to identify and learn from patterns in large sets of data. CNNs can also be used to improve the accuracy of predictions, by combining smart predictive analytics with real-world data. Vehicular network management can be improved, ensuring safer and more efficient communication across a distributed network.

## REFERENCES

- [1] O. Csillik and M. Kelly, "Identification of Citrus Trees from Unmanned Aerial Vehicle Imagery using Convolutional Neural Networks", *Drones*, Vol. 2, No. 4, pp. 1-39, 2018.
- [2] G. Kiruthiga, G.U. Devi and N.V. Kousik, "Analysis of Hybrid Deep Neural Networks with Mobile Agents for Traffic Management in Vehicular Adhoc Networks", CRC Press, 2020.
- [3] M. Shahverdy and M. Sabokrou, "Driver Behavior Detection and Classification using Deep Convolutional Neural Networks", *Expert Systems with Applications*, Vol. 149, pp. 113240-113254, 2020.
- [4] B. Al-Otaibi, N. Al-Nabhan and Y. Tian, "Privacy Preserving Vehicular Rogue Node Detection Scheme for Fog Computing", *Sensors*, Vol. 19, No. 4, pp. 965-982, 2019.
- [5] L. Forslof and H. Jones, "Roadroid: Continuous Road Condition Monitoring with Smart Phones", *Journal of Civil Engineering and Architecture*, Vol. 9, No. 4, pp. 485-496, 2015.
- [6] H. Tan, D. Choi, P. Kim, S. Pan and I. Chung, "Secure Certificateless Authentication and Road Message Dissemination Protocol in VANETs", *Wireless Communications and Mobile Computing*, Vol. 9, No. 2, pp. 1-14, 2018.
- [7] S.K Manju Bargavi, A Sharma and V Saravanan, "Routing Protocols in Vehicle Ad-Hoc Network", *Journal of Computational and Theoretical Nanoscience*, Vol. 17, No. 9-10, pp. 4559-4564, 2020.
- [8] T. Kiruthiga and J. Lloret, "A Novel Architecture of Intelligent Decision Model for Efficient Resource Allocation in 5G Broadband Communication Networks", *ICTACT Journal on Soft Computing*, Vol. 13, No. 3, pp. 2986-2994, 2023.
- [9] K.N. Kumar and C.K. Mohan, "Open-Air Off-Street Vehicle Parking Management System using Deep Neural Networks: A Case Study", *Proceedings of International Conference on Communication Systems and Networks*, pp. 800-805, 2022.
- [10] C.D.N. Kumar and V. Saravanan, "A Survival Study on Energy Efficient and Secured Routing In Mobile Adhoc Network", *International Organization of Scientific Research Journal of Computer Engineering*, Vol. 2, No. 1, pp. 1-12, 2018.
- [11] S. Kannan and M. Gheisari, "Ubiquitous Vehicular Ad-Hoc Network Computing using Deep Neural Network with IoT-based Bat Agents for Traffic Management", *Electronics*, Vol. 10, No. 7, pp. 785-798, 2021.
- [12] Y.S. Chia, Z.W. Siew, H.T. Yew, S.S. Yang and K.T.K. Teo, "An Evolutionary Algorithm for Channel Assignment Problem in Wireless Mobile Networks", *ICTACT Journal on Communication Technology*, Vol. 3, No. 4, pp. 613-618, 2012.
- [13] K.T.K. Teo, R.K.Y. Chin, S.E. Tan, C.H. Lee and K.G. Lim, "Performance Analysis of Enhanced Genetic Algorithm based Network Coding in Wireless Networks", *Proceedings of 8<sup>th</sup> Asia Modelling Symposium*, pp. 213-218, 2014.
- [14] P. Vijayakumar, M. Azees, A. Kannan and L.J. Deborah, "Dual Authentication and Key Management Techniques for Secure Data Transmission in Vehicular Ad Hoc Network", *IEEE Transactions on Intelligent Transportation Systems*, Vol. 17, No. 4, pp. 1015-1028, 2016.